

RER15-4-1600

RER15-4-1600,
Maximum payload 15 kg with maximum reach 1625 mm.

■ Highlights

A specific application software of stamping could be integrated, which brings simple programming and operation, and enable customers quickly production launch; High stiffness robot body design improves the robot dynamic performance and stability in high-speed operation.

Applications

It can be used in handling operations (machine tending).

Industries

Suitable for metal parts, logistics and other industries.



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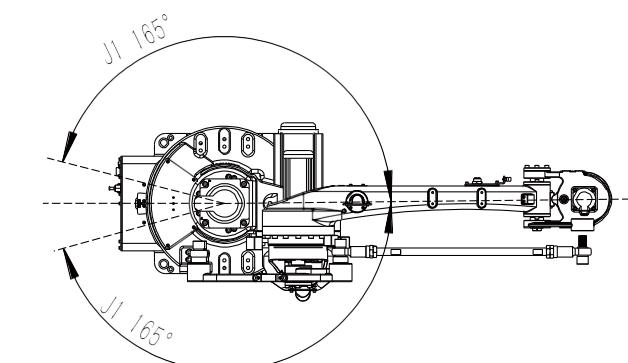
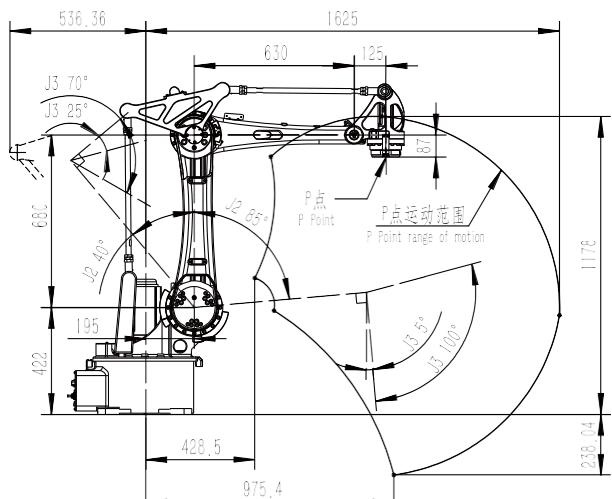
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SPECIFICATIONS

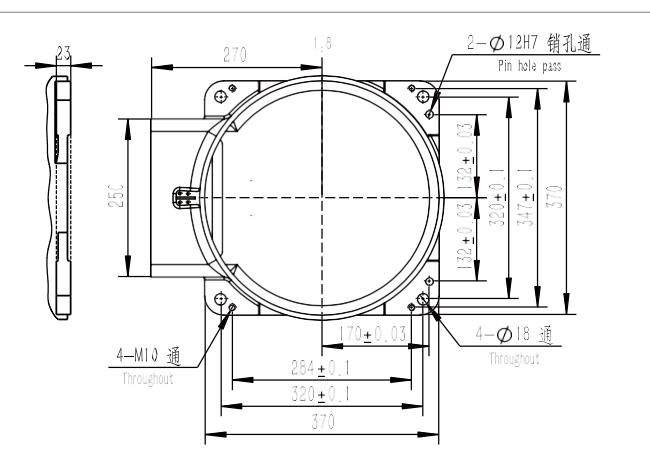
Model	RER15-4-1600	
Type	Articulated	
Controlled axes	4 Axes	
Max. payload on wrist	15 kg	
Repeatability	± 0.07 mm	
Robot weight	180 kg	
Reach	1625 mm	
Robot IP grade	IP54 / IP65 (Wrist)	
Cabinet IP grade	IP54	
Installation environment	Ambient temperature	0~45 °C
	Ambient humidity	RH≤80% (No dew nor frost allowed)
	Vibration acceleration	4.9 m/s ² (<0.5 G)

Drive mode	AC servo drive	
Installation	Floor	
Allowable load moment at wrist	J 4	27.5 N·m
Allowable load inertia at wrist	J 4	3.6 kg·m ²
Maximum speed	J 1	175°/sec
	J 2	165°/sec
	J 3	155°/sec
	J 4	330°/sec
Motion range	J 1	±165°
	J 2	+40°/85°
	J 3	+100°/70°
	J 4	±360°
J 2 + J 3	J 2 + J 3	-90°≤(J2+J3)≤+15°

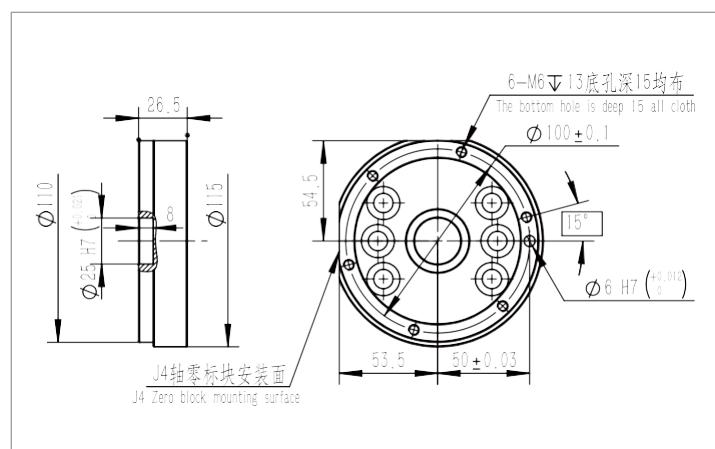
OPERATING SPACE



BASE MOUNTING SIZE



END FLANGE MOUNTING SIZE



Information Release Time 2023/09